

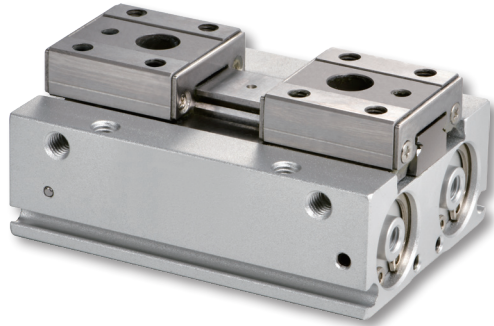
HDF series Low Profile Air Gripper

Product features/ Code of order

CHELIC

Feature

- Space saving and compact
- Double piston
- Height reduced 50% than HDZ



Specification

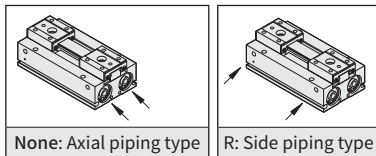
Item	Bore size (mm)	Ø12	Ø16	Ø20
Action		Double acting		
Fluid		Air		
Pressure range	kgf/cm ² (kPa)	1.5 ~ 7 (150 ~ 700)		
Ambient and fluid temperature	°C	0 ~ 60		
Max. operating frequency	time/min	100		
Lubrication	Cylinder	Lubrication free type		
	Slide rail	Lubrication required		
Closing stroke	mm	12, 24, 48	16, 32, 64	20, 40, 80
Port size		M5 x 0.8P		
Sensing device		With magnet		

Code of order **HDF R 16 x 32 - 9D 2**

1 2 3 4 5

1	Mark	Model
	None	Axial piping type
	R	Side piping type

● Image



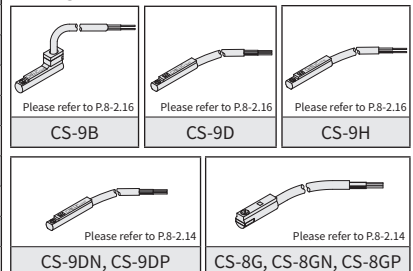
2	Mark	Bore size (mm)
	12	Ø12
	16	Ø16
	20	Ø20

3	Bore size (mm)	Stroke (mm)
	Ø12	12, 24, 48
	Ø16	16, 32, 64
	Ø20	20, 40, 80

4	Mark	Sensor switch
	None	Without sensor switch
	8G	CS-8G
	8GN	CS-8GN
	8GP	CS-8GP
	9D	CS-9D
	9B	CS-9B
	9H	CS-9H
	9DN	CS-9DN
	9DP	CS-9DP

5	Mark	Sensor quantity
	1	With 1 sensor switch
	2	With 2 sensor switches

● Image

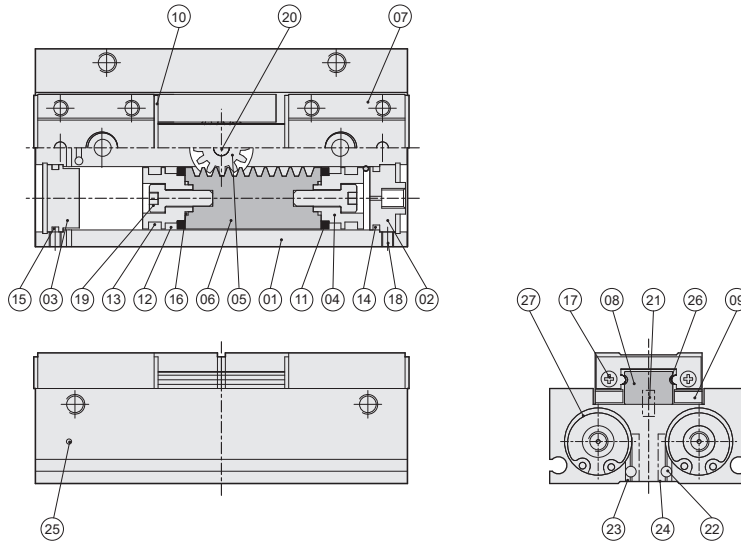


HDF series Low Profile Air Gripper

Product features

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Internal structure



Components and material list

No.	Item	Material	No.	Item	Material	No.	Item	Material
01	Body	Aluminum alloy	10	Roller block	Stainless steel	19	Piston rod screw	Alloy steel
02	Front cover	Aluminum alloy	11	Magnetic	Rare earth material	20	Gear pin	Bearing steel
03	Rear cover	Aluminum alloy	12	Wear ring	POM	21	Slide rail pin	Bearing steel
04	Piston	Aluminum alloy	13	Piston packing	NBR	22	Main air vent steel ball	Stainless steel
05	Gear shaft	Carbon steel	14	Front cover O-Ring	NBR	23	Front bottom air vent steel ball	Stainless steel
06	Gear	Stainless steel	15	Rear cover O-ring	NBR	24	Rear bottom air vent steel ball	Stainless steel
07	Slide base	Stainless steel	16	Piston O-ring	NBR	25	Side air vent steel ball	Stainless steel
08	Rail	Bearing steel	17	Roller block screw	Alloy steel	26	Steel ball	Stainless steel
09	Slide table stir slice	Stainless steel	18	Front cover screw	Alloy steel	27	Clip	Spring steel

Note: Gear rack material is POM (Polyoxymethylene) for HDF 12 & HDF 16

Packing and O-ring material list

Item	Piston packing	Front cover O-ring	Rear cover O-ring	Piston O-ring
Model \ Quantity	4	2	2	4
HDF Ø12	DYP - 12	Ø10 x Ø1	Ø10 x Ø1	Ø4 x Ø1
HDF Ø16	DYP - 16	Ø13.5 x Ø1.5	Ø14.5 x Ø1.5	Ø7.4 x Ø1.2
HDF Ø20	DYP - 20	Ø17.5 x Ø1.5	Ø17.5 x Ø1.5	Ø5.8 x Ø1.9

Unit: mm

Product weight

Model	HDF 12 x 12	HDF 12 x 24	HDF 12 x 48
Weight (kg)	0.15	0.19	0.27
Model	HDF 16 x 16	HDF 16 x 32	HDF 16 x 64
Weight (kg)	0.35	0.44	0.65
Model	HDF 20 x 20	HDF 20 x 40	HDF 20 x 80
Weight (kg)	0.64	0.85	1.22

Note: All of above are theoretical data. Weight tolerance about ±5%

HDQ

HDQT

HDQM

HMQ

HMT

HDL

HDT

HDF

RM

RB

HDF series Low Profile Air Gripper

Model selection

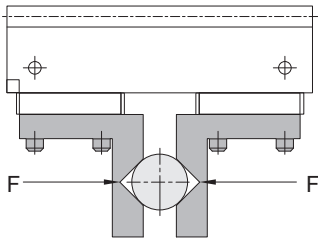
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Selection procedure

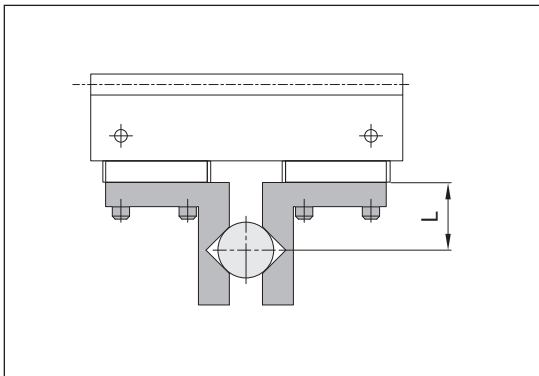


1 Confirm gripping force

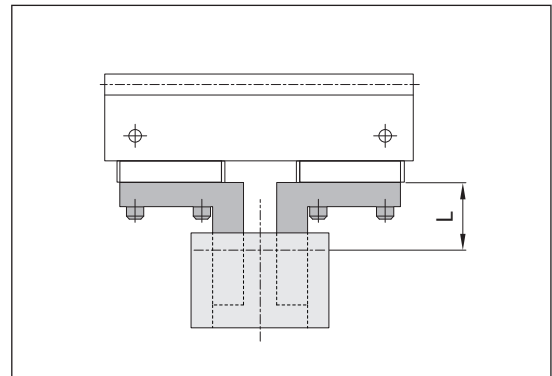
- Confirm gripping force: HDF series
- Expressing the effective gripping force



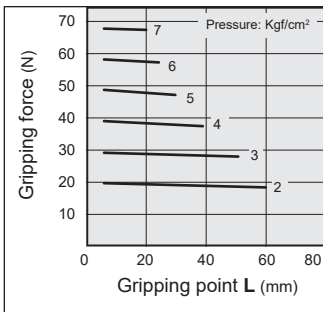
External gripping



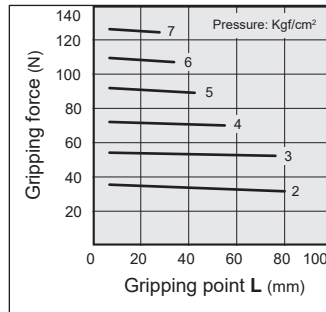
Internal gripping



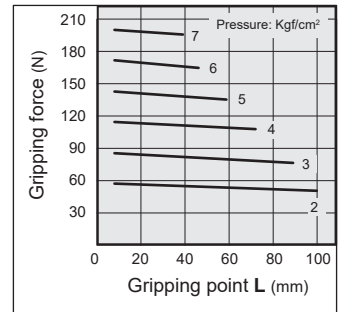
HDF 12



HDF 16



HDF 20



HDF series Low Profile Air Gripper

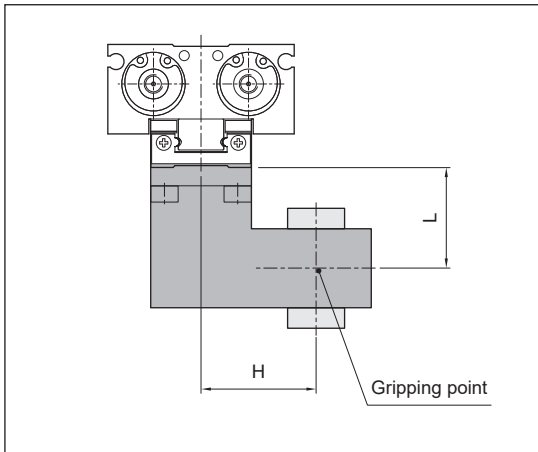
Model selection

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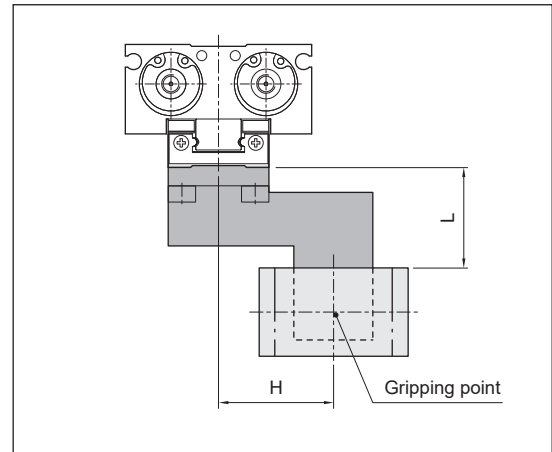
② Confirm gripping point

- Confirmation of the gripping position: HDF series
- The gripping position of a workpiece should be operated so that the amount of overhang(H) will stay the range given in the graphs below.
- If the gripping position of a workpiece over the range limits, this will have an adverse effect on the life of the gripper

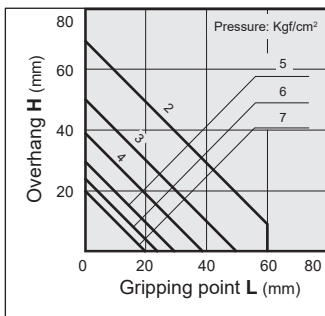
External gripping



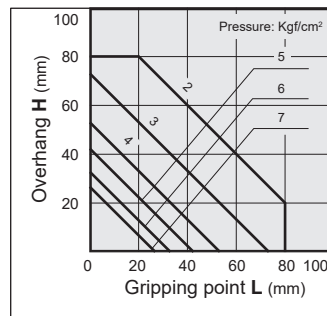
Internal gripping



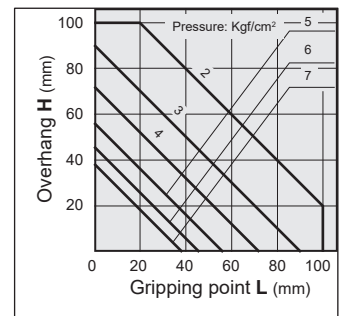
HDF 12



HDF 16



HDF 20



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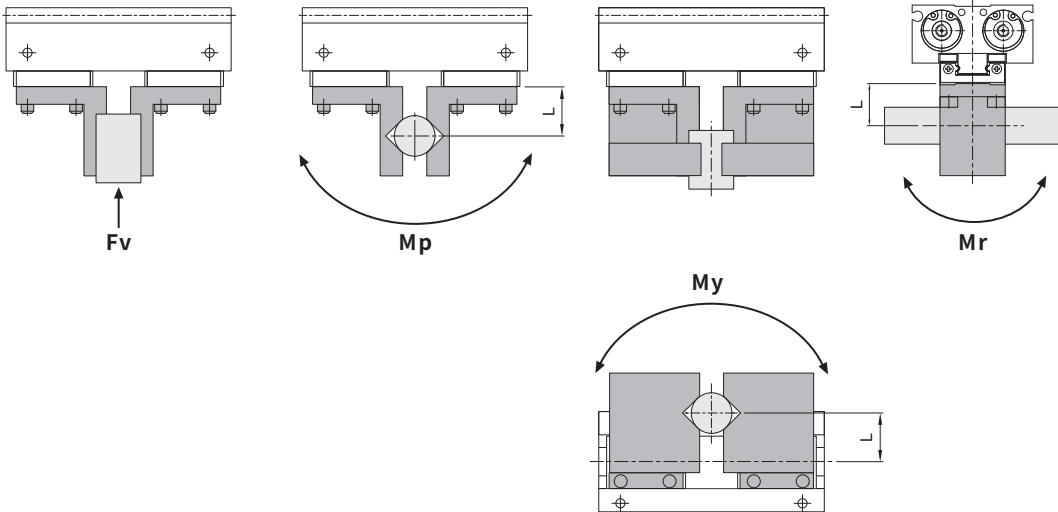
HDF series Low Profile Air Gripper

Model selection

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③ Confirm external force on fingers

- Confirmation of external force on fingers: HDF series



L: Distance to the point at which the load is applied

Model	Allowable vertical load Fv(N)	Maximum allowable moment		
		Mp (N·m)	My (N·m)	Mr (N·m)
HDF 12	98	0.68	0.68	1.4
HDF 16	176	1.4	1.4	2.8
HDF 20	294	2	2	4

Note: the load and moment values in the table is static values

Calculation of allowable external force (when moment load is applied)	Calculation examples
$\text{Allowable load } F(\text{N}) = \frac{M(\text{Maximum allowable moment}) (\text{N} \cdot \text{m})}{L \times 10^{-3}}$	<p>When a load $f= 10 \text{ N}$ operating, which applies pitch moment to point 30mm from the end of the HDF-12</p> $\text{Allowable load } F = \frac{1.4}{10 \times 10^{-3}} = 46.6 (\text{N})$ <p>$F = 46.6 > 10$ can be used</p>

HDF series Low Profile Air Gripper

Dimensions

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HDF 12

HDQ

HDQT

HDQM

HMQ

HMT

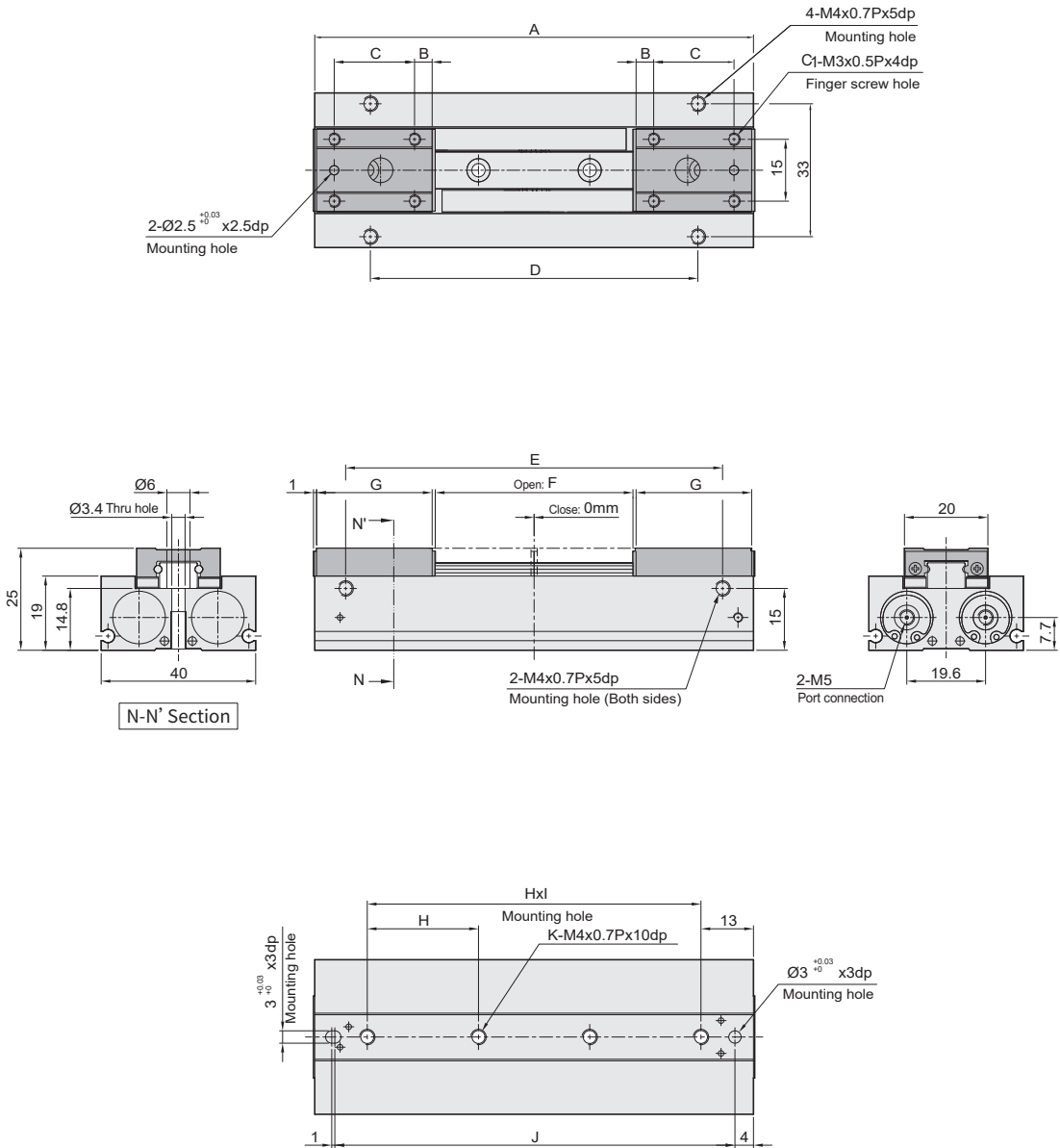
HDL

HDT

HDF

RM

RB



Unit: mm

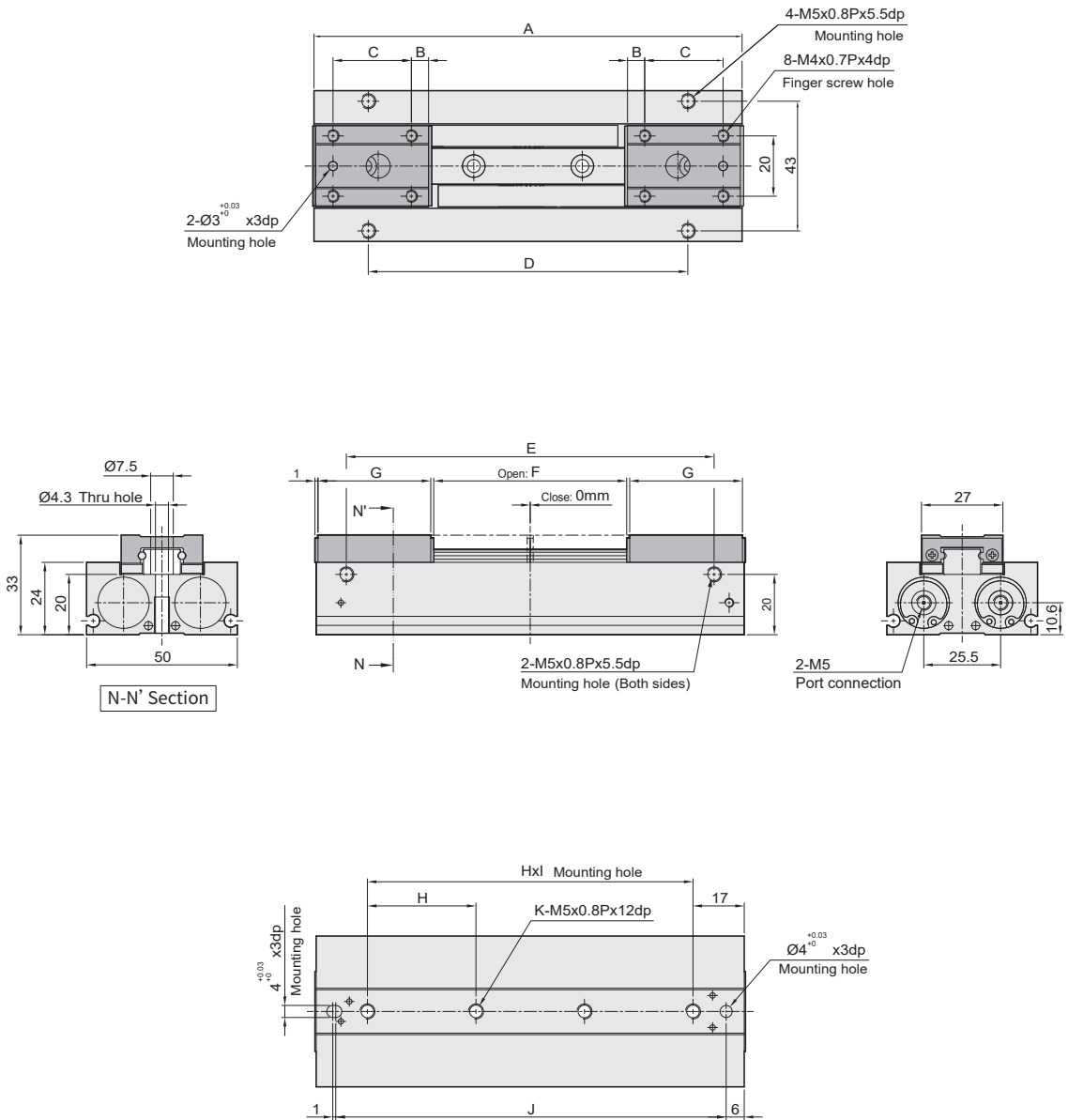
Model \ Mark	A	B	C	C ₁	D	E	F	G	H	I	J	K
HDF 12 x 12st	52	9	-	4	28	38	12	18	26	1	43.5	2
HDF 12 x 24st	68	4.5	12	8	44	54	24	21	42	1	59.5	2
HDF 12 x 48st	104	4.5	18	8	80	90	48	27	26	3	95.5	4

HDF series Low Profile Air Gripper

Dimensions

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HDF 16



Unit: mm

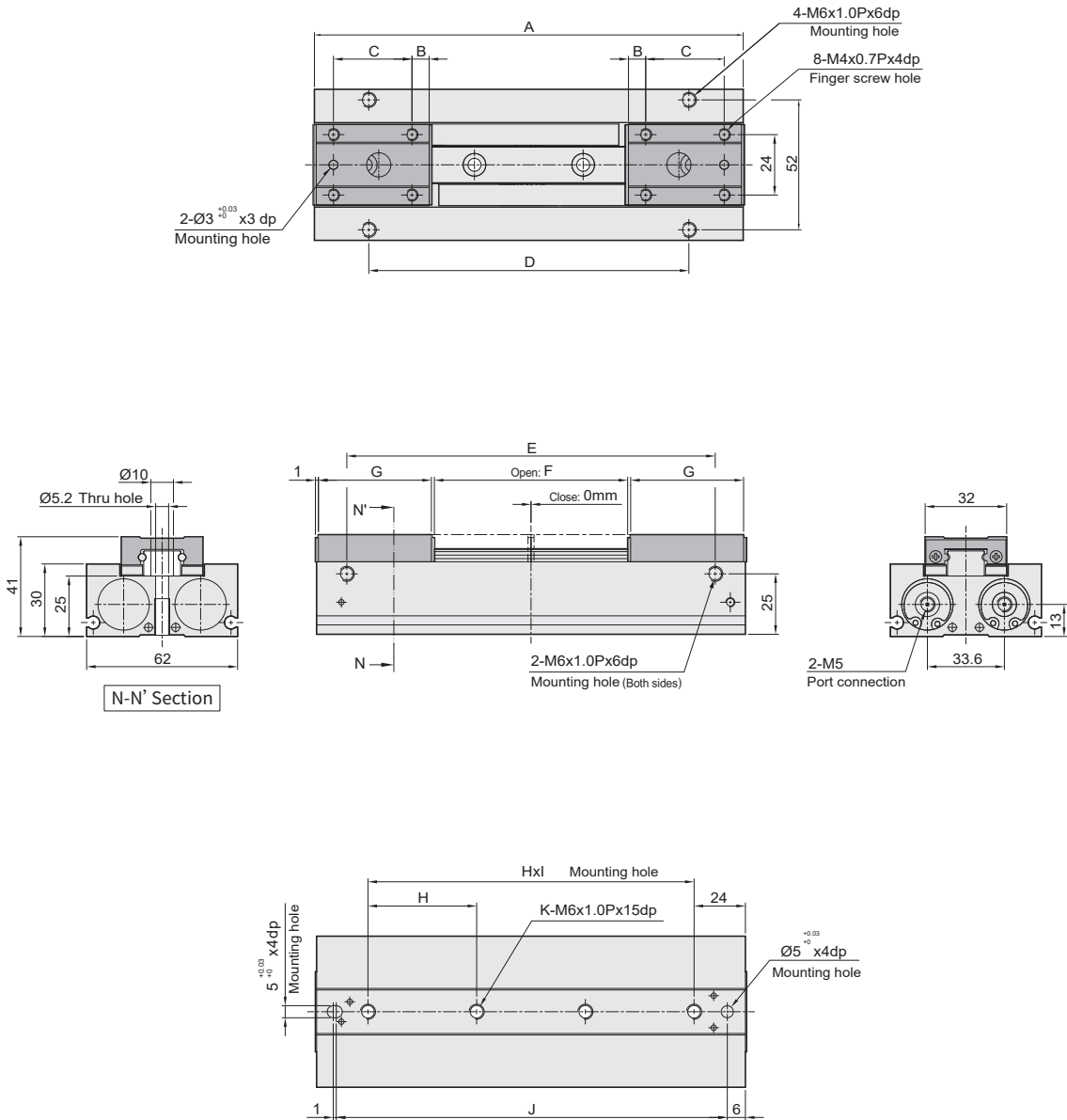
Model	Mark	A	B	C	D	E	F	G	H	I	J	K
HDF 16 x 16st		72	5.2	15	36	52	16	25.4	38	1	59.5	2
HDF 16 x 32st		94	5.7	18	58	74	32	29.4	60	1	81.5	2
HDF 16 x 64st		142	5.7	26	106	122	64	37.4	36	3	129.5	4

HDF series Low Profile Air Gripper

Dimensions

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HDF 20



HDQ

HDQT

HDQM

HMQ

HMT

HDL

HDT

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RM

RB

Unit: mm

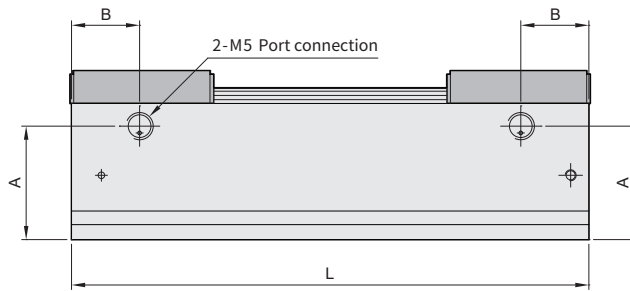
Model \ Mark	A	B	C	D	E	F	G	H	I	J	K
HDF 20 x 20st	86	7.6	16	40	56	20	31.2	38	1	73.5	2
HDF 20 x 40st	114	8.1	20	68	84	40	36.2	66	1	101.5	2
HDF 20 x 80st	174	8.1	30	128	144	80	46.2	42	3	161.5	4

HDF series Low Profile Air Gripper

Dimensions-Side piping type

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■ Side piping type



Unit: mm

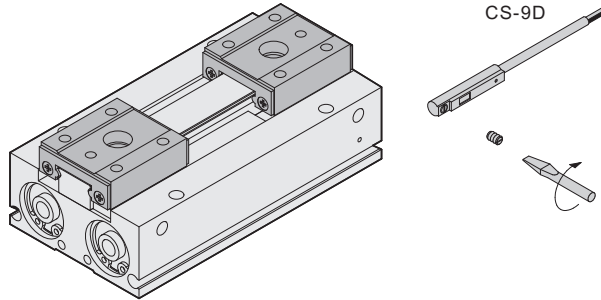
Model	Mark	L	A	B
HDF 12x12 ST		52	15	7
HDF 12x24 ST		68		
HDF 12x48 ST		104		
HDF 16x16 ST		72	20	10
HDF 16x32 ST		94		
HDF 16x64 ST		142		
HDF 20x20 ST		86	19	8.3
HDF 20x40 ST		114		
HDF 20x80 ST		174		

HDF series Low Profile Air Gripper

Mounting type and operation of sensor switch

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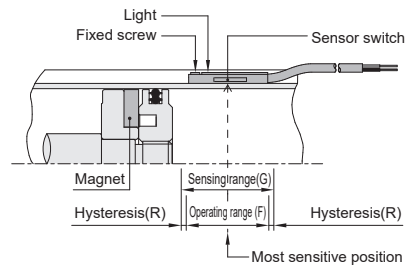
Sensor switch mounting type



Sensing range

Sensor switch is fixed on the cylinder body. The magnetic piston head will activate the sensor switch when it enters the operating range. It has 0.5mm differential.

Sensor switch setting and operating range



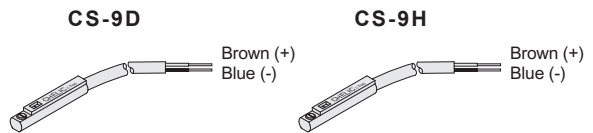
Operating range

When piston head moves the switch setting and adjustment will be based on the responding range generated by the magnetic field and the switch. (Please refer to the below table)

Unit: mm

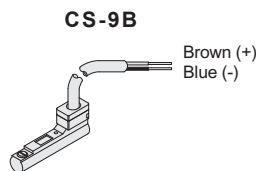
Model	CS-9D(B/H)	
Bore size	Operating range (F)	Hysteresis(R)
12	8	1
16	10	1.2
20	11	1.2

Sensor switch introduction



Voltage: DC 5~120V
AC 5~120V

Voltage: DC 5~240V
AC 5~240V



Voltage: DC 5~120V
AC 5~120V

HDQ

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HDQM

HMQ

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HDL

HDT

HDF

RM

RB